

## Making $S_y$ by Rotating $S_z$

Last time we saw

$$|\uparrow\rangle_x = \frac{1}{\sqrt{2}} |\uparrow\rangle_z + \frac{1}{\sqrt{2}} |\downarrow\rangle_z$$

and

$$|\downarrow\rangle_x = \frac{1}{\sqrt{2}} |\uparrow\rangle_z - \frac{1}{\sqrt{2}} |\downarrow\rangle_z$$

which means

$$\sqrt{2} |\uparrow\rangle_z = |\uparrow\rangle_x + |\downarrow\rangle_x$$

$$|\uparrow\rangle_z = \frac{1}{\sqrt{2}} (|\uparrow\rangle_x + |\downarrow\rangle_x)$$

and

$$|\downarrow\rangle_z = \frac{1}{\sqrt{2}} (|\uparrow\rangle_x - |\downarrow\rangle_x)$$

$$\begin{aligned} \langle \uparrow | \downarrow \rangle_z &= \left[ \frac{1}{\sqrt{2}} (\langle \uparrow | \uparrow \rangle_x + \langle \downarrow | \uparrow \rangle_x) \right] \left[ \frac{1}{\sqrt{2}} (|\uparrow\rangle_x - |\downarrow\rangle_x) \right] \\ &= \frac{1}{2} [\langle \uparrow | \uparrow \rangle_x - \cancel{\langle \uparrow | \downarrow \rangle_x} + \cancel{\langle \downarrow | \uparrow \rangle_x} - \langle \downarrow | \downarrow \rangle_x] \end{aligned}$$

by 1 or add to zero!

$$= \frac{1}{2} [1 - 1] = 0 \text{ as it should}$$

We similarly saw that

$$|\uparrow\rangle_y = \frac{1}{\sqrt{2}} [ |\uparrow\rangle_z + i |\downarrow\rangle_z ]$$

and

$$|\downarrow\rangle_y = \frac{1}{\sqrt{2}} [ |\uparrow\rangle_z - i |\downarrow\rangle_z ]$$

Now, let's return to our ideas of angular momentum as the generator of rotations to do this another way:

Say  $|\psi\rangle = |\uparrow\rangle_z$

We'll take  $\phi \rightarrow \pi/2$

Now, let's rotate by  $\phi$  about  $\hat{x}$  to  $|\psi'\rangle$

Ex: Write the expression

$$|\psi'\rangle = \exp\left[-\frac{i\phi}{\hbar} \vec{S} \cdot \hat{n}\right] |\psi\rangle$$

in our case  $\hat{n} = \hat{y}$

$$\therefore |\psi'\rangle = \exp\left[-\frac{i\phi}{\hbar} S_x\right] |\psi\rangle$$

$$= \exp\left[-\frac{i\phi}{\hbar} \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}\right] |\uparrow\rangle$$

Expand the exponential as that is the definition of  $e^M$ :

$$|\psi'\rangle = \left[ 1 + \left(\frac{-i\varphi}{2}\right) \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \frac{1}{2!} \left(\frac{-i\varphi}{2}\right)^2 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^2 + \frac{1}{3!} \left(\frac{-i\varphi}{2}\right)^3 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^3 + \frac{1}{4!} \left(\frac{-i\varphi}{2}\right)^4 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^4 + \dots \right] \begin{pmatrix} 1 \\ 0 \end{pmatrix}_z$$

We need the  $z$ -basis representation of  $S_y$  as that is the basis of our ket (Our ket is in the  $S_z$  vector-space).

Note  $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}^2 = \mathbb{1}_{2 \times 2}$  (true for all  $\sigma_i$ 's!)

$$\therefore \sigma_x^{2n+1} = \sigma_x$$

Writing  $|\uparrow\rangle_z$  as  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  to be more explicit:

$$|\psi'\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \frac{1}{1!} \left(\frac{-i\varphi}{2}\right) \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \frac{1}{2!} \left(\frac{-i\varphi}{2}\right)^2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \frac{1}{3!} \left(\frac{-i\varphi}{2}\right)^3 \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \frac{1}{4!} \left(\frac{-i\varphi}{2}\right)^4 \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \dots$$

or

$$|\psi'\rangle = |\uparrow\rangle + \left(\frac{-i\varphi}{2}\right) |\downarrow\rangle + \frac{1}{2!} \left(\frac{-i\varphi}{2}\right)^2 |\uparrow\rangle + \frac{1}{3!} \left(\frac{-i\varphi}{2}\right)^3 |\downarrow\rangle + \frac{1}{4!} \left(\frac{-i\varphi}{2}\right)^4 |\uparrow\rangle + \dots$$

$$|\psi'\rangle = \left[ 1 - \frac{1}{2!} \left(\frac{-i\varphi}{2}\right)^2 + \frac{1}{4!} \left(\frac{-i\varphi}{2}\right)^4 - \dots \right] |\uparrow\rangle + \left[ -i \left(\frac{\varphi}{2}\right) + i \frac{1}{3!} \left(\frac{\varphi}{2}\right)^3 - \dots \right] |\downarrow\rangle$$

$$|\psi'\rangle = \cos\left(\frac{\varphi}{2}\right) |\uparrow\rangle - i \sin\left(\frac{\varphi}{2}\right) |\downarrow\rangle$$

$$\varphi \rightarrow \frac{\pi}{2}$$

$$|\psi'\rangle = \cos\left(\frac{\pi}{4}\right) |\uparrow\rangle - i \sin\left(\frac{\pi}{4}\right) |\downarrow\rangle$$

$$= \frac{1}{\sqrt{2}} [|\uparrow\rangle - i|\downarrow\rangle] = |\downarrow\rangle_y \text{ o.e.}\delta$$

## Addition of Angular Momentum

• Talk about orbital and spin so have something

$$\vec{J} = \vec{L} + \vec{S} \quad \text{to speak in}$$

$$\rightarrow J_y = L_y + S_y$$

$$\rightarrow J_x = L_x + S_x$$

$$\rightarrow J_z = L_z + S_z$$

We can tell if  $\vec{J}$  is an angular momentum because if it follows commutations

$$\begin{aligned} \rightarrow [J_x, J_y] &= [L_x + S_x, L_y + S_y] \\ &= [L_x, L_y] + [L_x, S_y] + [L_y, S_x] + [S_x, S_y] \end{aligned}$$

\* because we can know  $S_y$  and  $L_x$

$$\rightarrow [J_x, J_y] = i\hbar L_z + i\hbar S_z = i\hbar J_z$$

All raising/lowering etc. still work

$$\vec{J}^2 = J_x^2 + J_y^2 + J_z^2 = L^2 + 2\vec{L} \cdot \vec{S} + S^2$$

Lets play: Hydrogenic  $e^-$  in  $2p$  state  
 $\rightarrow l=1$

$\rightarrow l$  not really needed

$$[J^2, S_z] = ?$$

$$\rightarrow [L^2 + (2L_x S_x + 2L_y S_y + 2L_z S_z) + S^2, S_z]$$



do not commute

$$\rightarrow \therefore [J^2, S_z] \neq 0$$

$$\rightarrow \text{Similarly } [J^2, L_z] \neq 0$$

$$[J^2, L^2] = 0$$

$$[J^2, S^2] = 0$$

Could have basis states  $|l s m_l m_s\rangle$

$\rightarrow l$  and  $s$  often omitted because they are obvious

or could write  $|l s j m_j\rangle$

## Adding 2 Angular Momenta

- All angular momenta work the same
- Call one  $L$  and one  $S$  for argument
- Recall that:
  - $J^2, J_z, L^2, S^2$  commute
  - $L_z$  and  $S_z$  do not commute with  $J^2$
  - $L^2, S^2, L_z, S_z$  all commute

### 2 Distinguishable spin $1/2$ particles

$$S_i^2 |\Psi\rangle = \hbar^2 \left(\frac{1}{2}\right)\left(\frac{1}{2}+1\right) |\Psi\rangle$$

- $m_i = 1/2$  or  $-1/2$
- $m_j = 1/2$  or  $-1/2$

Can write a wave function as  $|S_1^2 S_2^2 S_{1z} S_{2z}\rangle$

- $\rightarrow = |1/2, 1/2 \pm 1/2, \pm 1/2\rangle$
- $\rightarrow$  since  $S_1^2$  and  $S_2^2$  always =  $\hbar^2$  will ignore
- $\rightarrow$  use  $\uparrow\downarrow$ 's for  $+1/2$  and  $-1/2$  respectively

Basis set (uncoupled)  $|\Psi\rangle = \alpha|\uparrow\uparrow\rangle + \beta|\uparrow\downarrow\rangle + \gamma|\downarrow\uparrow\rangle + \delta|\downarrow\downarrow\rangle$

- $\rightarrow |\uparrow\uparrow\rangle \quad S_z = +1$
- $\rightarrow |\uparrow\downarrow\rangle \quad S_z = 0$
- $\rightarrow |\downarrow\uparrow\rangle \quad S_z = 0$
- $\rightarrow |\downarrow\downarrow\rangle \quad S_z = -1$

$S_z$  is a diagonal matrix since this basis

$$\hat{S}_z = \hbar \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}$$

$$+ \rightarrow \hbar \sqrt{l(l+1) - m(m+1)}$$

$$- \rightarrow \hbar \sqrt{l(l+1) - m(m-1)}$$

$$\frac{3}{4} - \frac{1}{4}(\frac{1}{2}+1)$$

$$\frac{3}{4} - \frac{3}{4}$$

What about  $\vec{S}^2$ ?

$$\rightarrow \vec{S}^2 = (\vec{S}_1 + \vec{S}_2)^2$$

commuting not a problem

$$\rightarrow \vec{S}^2 = (\vec{S}_1 \cdot \vec{S}_1 + \vec{S}_2 \cdot \vec{S}_2 + 2\vec{S}_1 \cdot \vec{S}_2)$$

$$\rightarrow S^2 = S_1^2 + S_2^2 + 2(S_{1x}S_{2x} + S_{1y}S_{2y} + S_{1z}S_{2z})$$

-)

$$\rightarrow S^2 = S_1^2 + S_2^2 + 2S_{1z}S_{2z} + S_{1+}S_{2-} + S_{1-}S_{2+}$$

Identity:  $\frac{1}{2}(S_{1+}S_{2-} + S_{1-}S_{2+})$

-) good form because we know how all of these operators act on  $\psi$ 's

Ex

$$S^2 |\uparrow\uparrow\rangle$$

$$\rightarrow (S_1^2 + S_2^2 + 2S_{1z}S_{2z} + S_{1+}S_{2-} + S_{1-}S_{2+}) |\uparrow\uparrow\rangle$$

$$\rightarrow \hbar^2 \left[ \frac{3}{4} |\uparrow\uparrow\rangle + \frac{3}{4} |\uparrow\uparrow\rangle + \frac{1}{2} |\uparrow\uparrow\rangle + 0 + 0 \right]$$

$$\rightarrow \hbar^2 2 |\uparrow\uparrow\rangle$$

$$\rightarrow s(s+1) = 2$$

$$\rightarrow s = 1 \leftarrow \text{was } \frac{1}{2} + \frac{1}{2}$$

$$\rightarrow \dots |\uparrow\uparrow\rangle \text{ has:}$$

$$* S_\psi = \frac{1}{2}$$

$$* S_L = \frac{1}{2}$$

$$* m_1 = \frac{1}{2}$$

$$* m_2 = \frac{1}{2}$$

$$* \text{AND } s = 1$$

Similarly for  $|\uparrow\downarrow\rangle$ :

$$\rightarrow S^2 |\uparrow\downarrow\rangle = \hbar^2 \left[ \frac{3}{4} |\uparrow\downarrow\rangle + \frac{3}{4} |\uparrow\downarrow\rangle - \frac{1}{2} |\uparrow\downarrow\rangle + 0 + |\downarrow\uparrow\rangle \right]$$

$$\rightarrow = \hbar^2 \left[ \frac{3}{4} |\uparrow\downarrow\rangle + \frac{3}{4} |\uparrow\downarrow\rangle - \frac{1}{2} |\uparrow\downarrow\rangle + 0 + |\downarrow\uparrow\rangle \right]$$

-) This is not an eigenstate of  $S^2$ !! b/c  
For  $|\downarrow\uparrow\rangle$   $S^2$  comes out to be  $|\uparrow\downarrow\rangle + |\downarrow\uparrow\rangle$



In a matrix  $\uparrow \uparrow$

$$S^2 = \hbar^2 \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

→ We need eigenvectors and eigenvalues for

\* done before

$$\begin{pmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{pmatrix} \quad \begin{pmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{pmatrix}$$

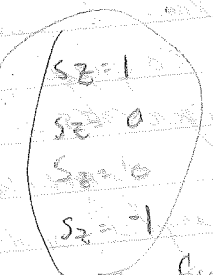
$\lambda = 2$                        $\lambda = 0$

These  $\lambda$ 's can be used via  $\lambda = s(s+1)$  to get the  $s$  values for these states

→  $S^2$  eigen states

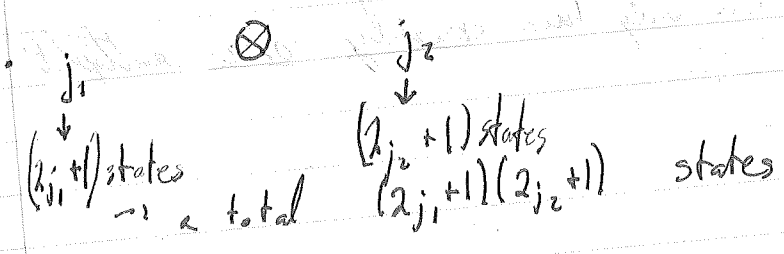
$$\begin{aligned} &|\uparrow\uparrow\rangle \\ &\frac{1}{\sqrt{2}}|\uparrow\downarrow\rangle + \frac{1}{\sqrt{2}}|\downarrow\uparrow\rangle \\ &\frac{1}{\sqrt{2}}|\uparrow\downarrow\rangle - \frac{1}{\sqrt{2}}|\downarrow\uparrow\rangle \\ &|\downarrow\downarrow\rangle \end{aligned}$$

- $s=1$        $S_z = 1$
- $s=1$        $S_z = 0$
- $s=0$        $S_z = 0$
- $s=1$        $S_z = -1$



from applying  $S_z$  matrix to state values are in order

## General Angular Momentum Addition



$$\begin{aligned}
 j_1 & \quad m_1 = -j_1, -j_1+1, \dots, +j_1 \\
 j_2 & \quad m_2 = -j_2, -j_2+1, \dots, +j_2 \\
 \text{maximum } m & = j_1 + j_2 \quad m_j = j_1 + j_2
 \end{aligned}$$

$$\therefore m_j \leq j_1 + j_2$$

$$|j_1 \quad j_2\rangle = \text{only way to get } m = j_1 + j_2$$

Commuting operators:

- Uncoupled  $J_1^2, J_1z, J_2^2, J_2z$
- Coupled  $J^2, Jz$

BUT  $[J^2, J_{1z}] \neq 0$

- I know I can find a basis of eigenstates of coupled  $J$

- eigenstates of coupled  $J$  must be linear combinations of uncoupled states

- uncoupled states we just list of possibilities

Eigenstates of  $J^2$  ~~are~~ come in multiplets of  $m = -j, \dots, +j$  which has  $(2j+1)$  elements

Cannot have  $j > j_1 + j_2$  as that would imply an  $m$  greater than  $j_1 + j_2$  which we have shown you cannot do

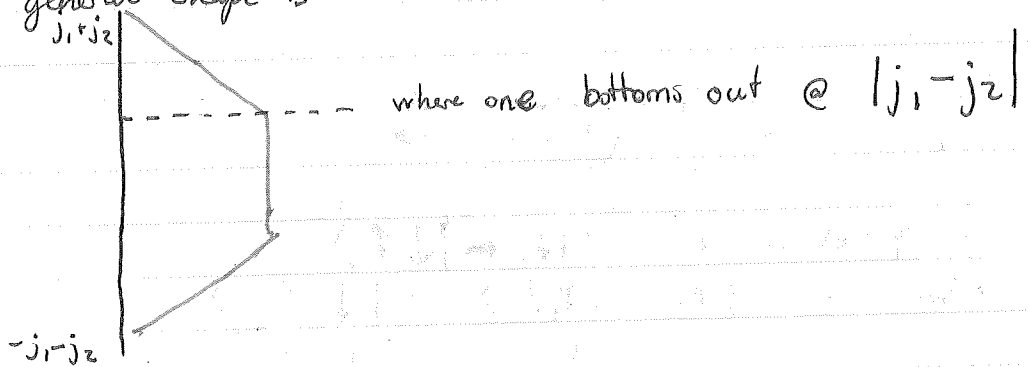
- Similarly  $j$  cannot be  $< j_1 + j_2$  because then  $\nexists$  an  $m = j_1 + j_2$

- In fact can only have exactly one multiplet with  $j_1 + j_2 = j$ .

$m \equiv m_1 + m_2$	$  \begin{matrix} m_1 & m_2 \end{matrix} \rangle$	
$j_1 + j_2$	$  j_1, j_2 \rangle$	(1 state)
$j_1 + j_2 - 1$	$  (j_1 - 1), j_2 \rangle$ or $  j_1, (j_2 - 1) \rangle$	(2 states)
$j_1 + j_2 - 2$	$  (j_1 - 2), j_2 \rangle;   j_1, (j_2 - 2) \rangle;   (j_1 - 1), (j_2 - 1) \rangle$	(3 states)
$j_1 + j_2 - 3$		(4 states)
$j_1 + j_2 - 4$		(5 states)

→ until  $j_1 - X = -j_1$  or  $j_2 - X = -j_2$   
 \* i.e. cannot lower one ~~any more~~ anymore

→ general shape is



$$j_1 \otimes j_2 = j_1 + j_2 \oplus j_1 + j_2 - 1 \oplus j_1 + j_2 - 2 \oplus \dots \oplus |j_1 - j_2|$$

↑ just list elements

### In Cartesian Coordinates

$$l_1 = 1 \quad l_2 = 1$$

$l_2 = 2, 1, 0$  with 9 states

$$\begin{pmatrix} p_x \\ p_y \\ p_z \end{pmatrix} \otimes \begin{pmatrix} q_x \\ q_y \\ q_z \end{pmatrix} = \begin{pmatrix} p_x q_x \\ p_x q_y \\ p_x q_z \\ p_y q_x \\ \vdots \\ p_z q_z \end{pmatrix}$$

Conjecture: When  $l=1$  need 3 possibilities so  $\vec{p} \times \vec{q}$   
Conjecture: When  $l=0$  need 1 possibility so  $\vec{p} \cdot \vec{q}$

When  $l=2$

$$= \frac{1}{3} \vec{p} \cdot \vec{q} \mathbb{I}_{3 \times 3} + \begin{pmatrix} p_x q_y - p_y q_x & & \\ & p_x q_z - p_z q_x & \\ & & 0 \end{pmatrix}$$